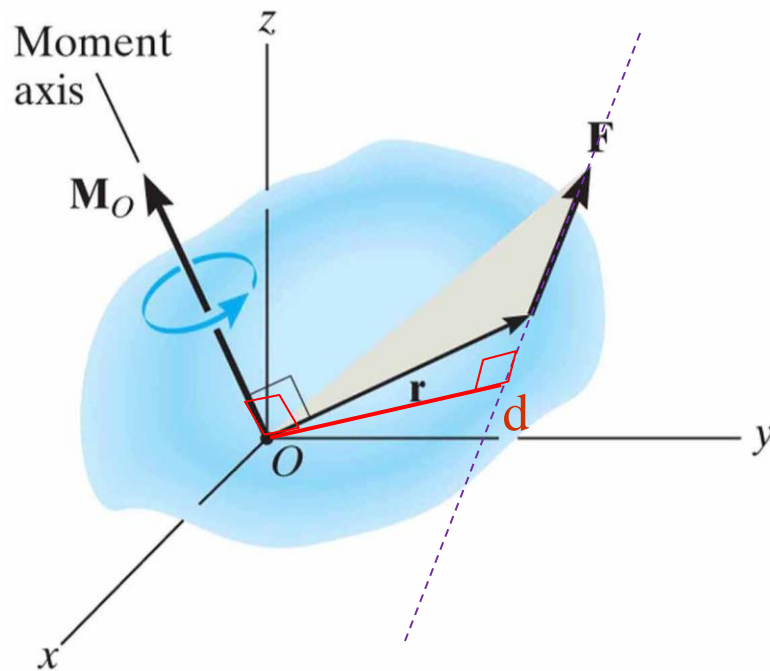


# Vector Moment Analysis (4.2 - 4.4)



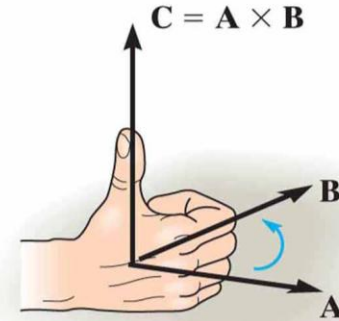
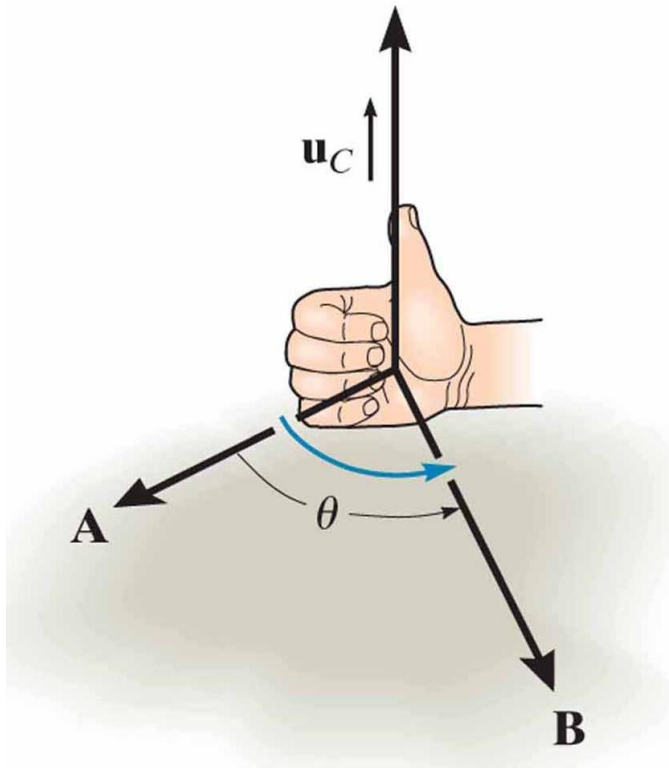
$$M_O = F d$$

$$M_O \perp F \perp d$$

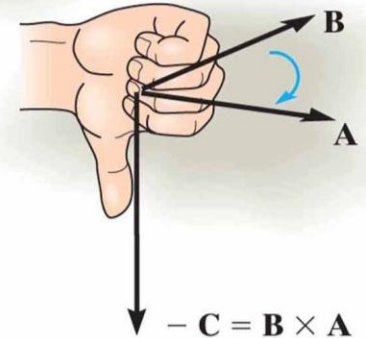
- Magnitude of moment is still given by product of force and perpendicular distance.
- Direction is perpendicular to line of F and d.
- Can be difficult to determine in 3D using scalars.

# Vector (Cross) Product

$$\mathbf{C} = \mathbf{A} \times \mathbf{B}$$



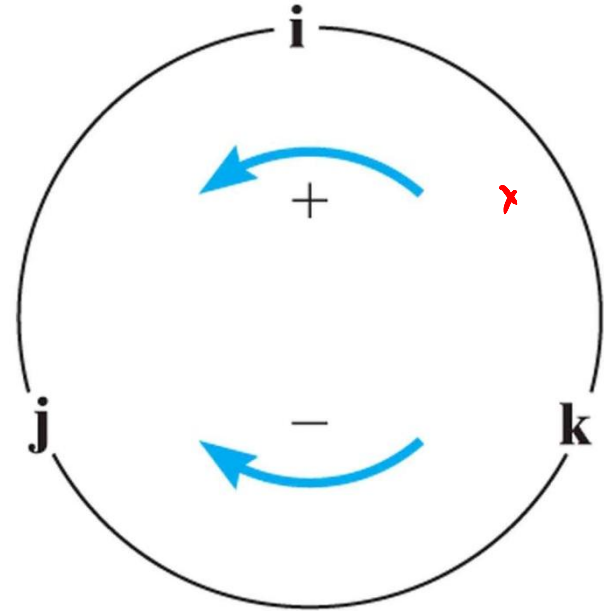
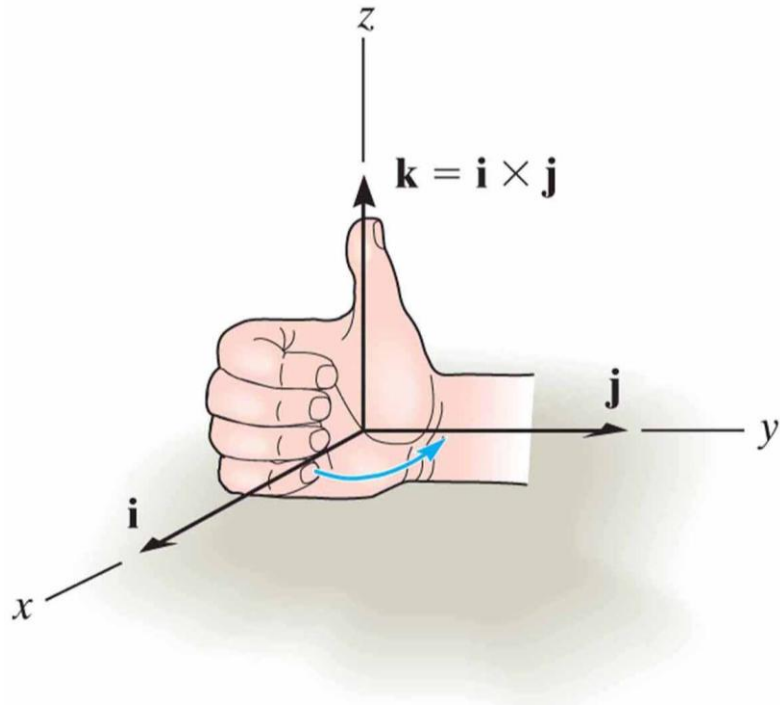
$$\mathbf{A} \times \mathbf{B} = -(\mathbf{B} \times \mathbf{A})$$



Vector product of two vectors  $\mathbf{A}$  and  $\mathbf{B}$  is vector  $\mathbf{C}$ :

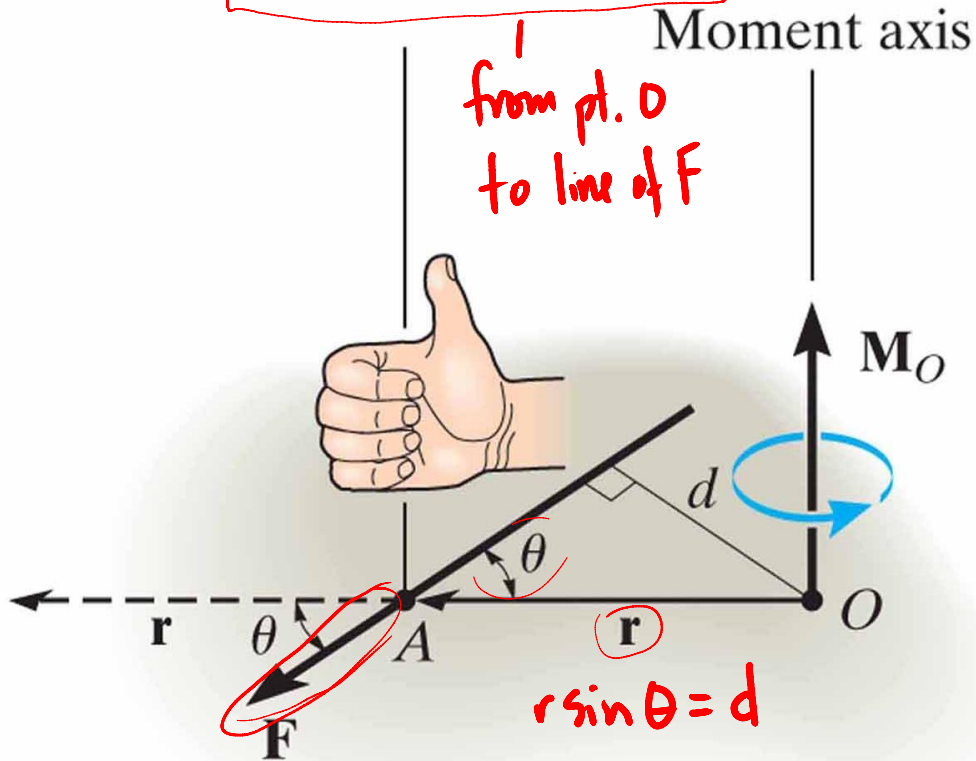
1. Line of action of  $\mathbf{C}$  is perpendicular to plane of  $\mathbf{A}$  and  $\mathbf{B}$ .
2. Magnitude of  $\mathbf{C}$  is  $C = AB \sin \theta$
3. Direction of  $\mathbf{C}$  is obtained from the right-hand rule.

# Cartesian Unit Vectors



$$\hat{i} \times \hat{j} = \hat{k}$$
$$\hat{j} \times \hat{i} = -\hat{k}$$

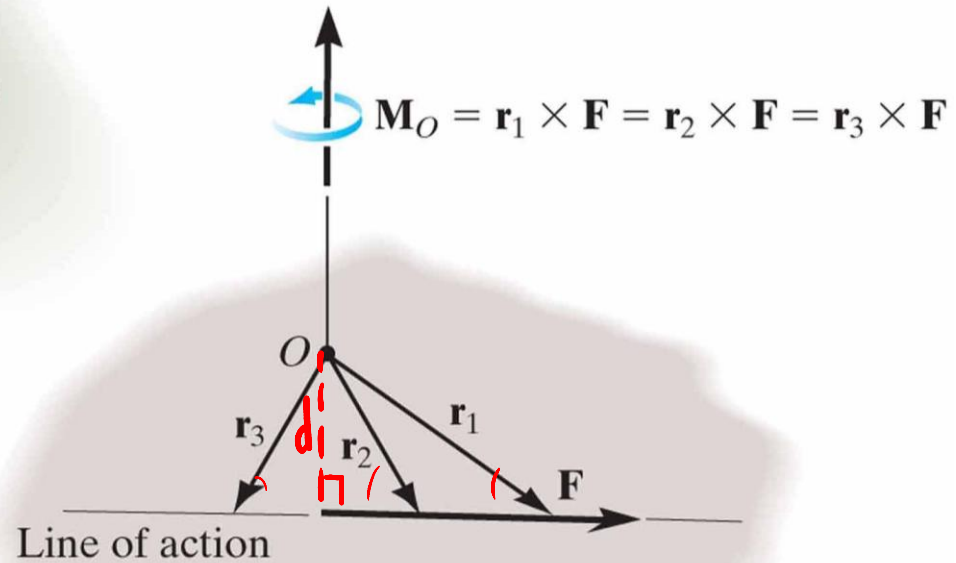
$$\vec{M}_O = \vec{r} \times \vec{F}$$



Magnitude of  $M_O$

$$M_O = r F \sin \theta$$

$$M_O = F d$$

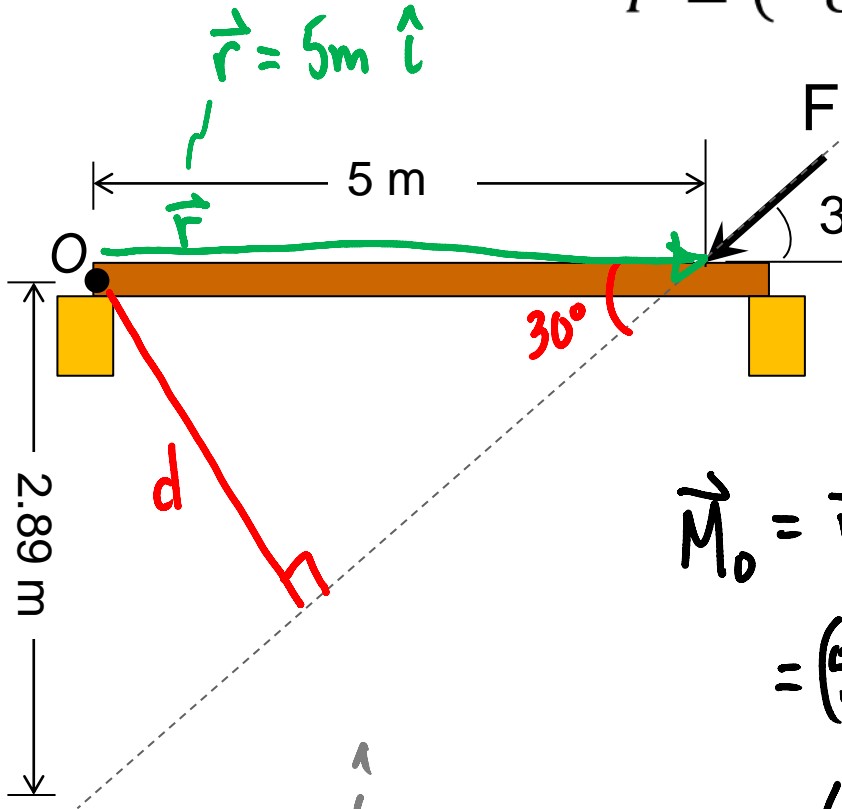


Any position vector  $\mathbf{r}$  that connects  $O$  to line of  $\mathbf{F}$  gives same result.

# Example in 2D: Find $M_O$



$$\vec{F} = (-86.6\hat{i} - 50\hat{j}) \text{ N}$$



$$d = 5 \text{ m} \sin 30^\circ = 2.5 \text{ m}$$

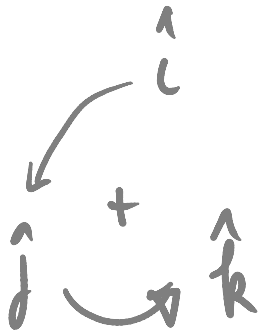
$$M_O = Fd = 100 \text{ N} (2.5 \text{ m}) = \boxed{250 \text{ Nm} \downarrow (-)}$$

$$\vec{M}_O = \vec{r} \times \vec{F}$$

$$= (5 \text{ m}) \hat{i} \times (-86.6 \hat{i} - 50 \hat{j}) \text{ N}$$

$$= (5)(-86.6) \hat{i} \times \hat{i} + \hat{k}$$

$$+ (5 \text{ m})(-50 \text{ N}) \hat{i} \times \hat{j} = \boxed{-250 \hat{k} \text{ Nm}}$$



# Evaluating Cross Products

$$\vec{M}_O = \vec{r} \times \vec{F}$$

$$\vec{r} = r_x \hat{i} + r_y \hat{j} + r_z \hat{k}$$

$$\vec{F} = F_x \hat{i} + F_y \hat{j} + F_z \hat{k}$$

$= \det$

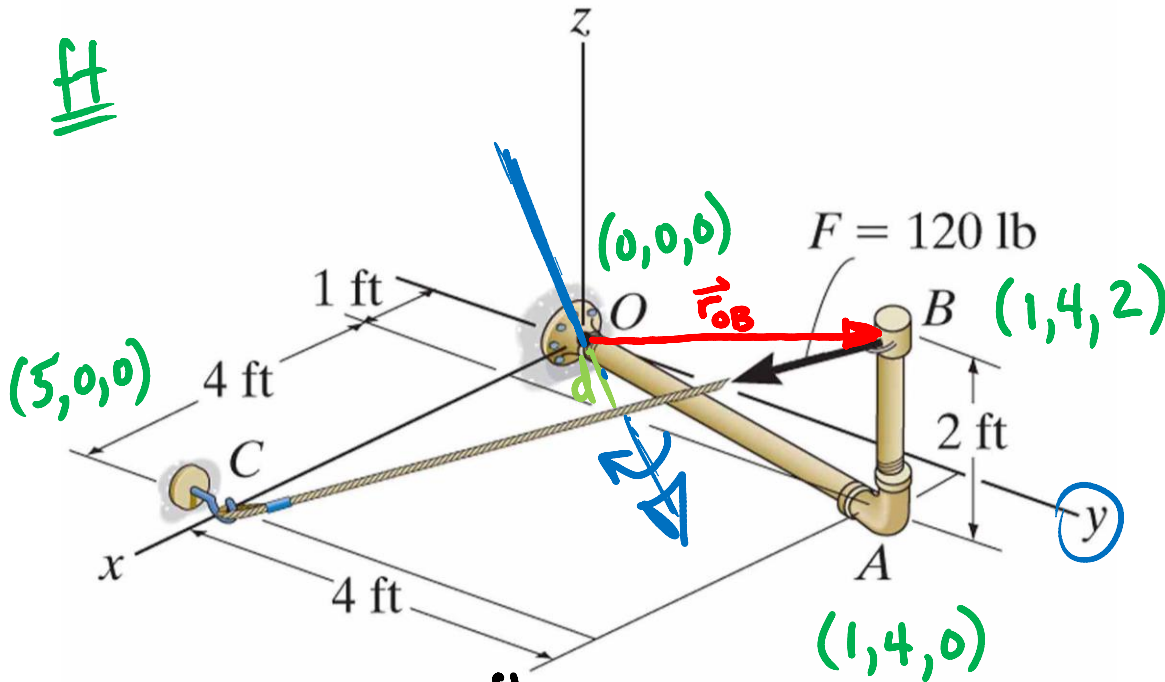
	(+)		(-)		
	$\hat{i}$	$\hat{j}$	$\hat{k}$	$\hat{i}$	$\hat{j}$
	$r_x$	$r_y$	$r_z$	$r_x$	$r_y$
	$F_x$	$F_y$	$F_z$	$F_x$	$F_y$

$= (r_y F_z - r_z F_y) \hat{i} + (r_z F_x - r_x F_z) \hat{j} + (r_x F_y - r_y F_x) \hat{k}$

Example 2a: Find moment of F about point O

$\vec{M}_O$

ft



$$\vec{M}_O = \vec{r}_{OB} \times \vec{F}$$

$$\vec{r}_{OB} = (\hat{i} + 4\hat{j} + 2\hat{k}) \text{ ft}$$

$$\vec{F} = F \vec{u}_{BC}$$

$$\vec{u}_{BC} = \frac{\vec{r}_{BC}}{r_{BC}} = \frac{(C-B)}{r_{BC}}$$

$$= \frac{(5-1)\hat{i} + (0-4)\hat{j} + (0-2)\hat{k}}{\sqrt{4^2 + 4^2 + 2^2}}$$

$$\vec{r}_O \times \vec{F} = (\hat{i} + 4\hat{j} + 2\hat{k}) \times (120 \text{ lb}) \left( \frac{2}{3}\hat{i} - \frac{2}{3}\hat{j} - \frac{1}{3}\hat{k} \right)$$

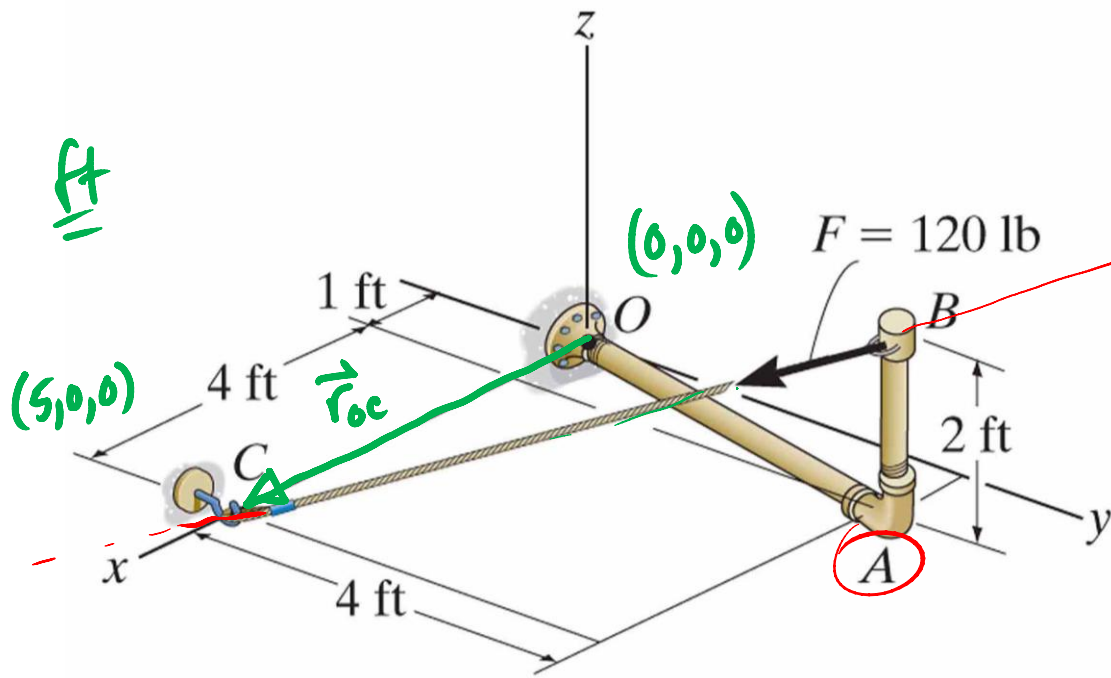
$$= \text{ft} \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 4 & 2 \\ 80 & -80 & -40 \end{vmatrix} = (-160 + 160)\hat{i} + (160 + 40)\hat{j} + (-80 - 320)\hat{k}$$

$$\vec{u}_{BC} = \frac{2}{3}\hat{i} - \frac{2}{3}\hat{j} - \frac{1}{3}\hat{k}$$

$$\vec{M}_O = (200\hat{j} - 400\hat{k}) \text{ lb}\cdot\text{ft}$$

$$M_O = 447 \text{ lb}\cdot\text{ft}$$

**Example 2a'**: Find moment of  $F$  about point  $O$



$$\vec{M}_O = \vec{r}_{OC} \times \vec{F}$$

$$\vec{F} = (80\hat{i} - 80\hat{j} - 40\hat{k}) \text{ lb}$$

$$\vec{r}_{OC} = 5\hat{i} \text{ ft}$$

$$= 5\hat{i} \times (80\hat{i} - 80\hat{j} - 40\hat{k}) \text{ ft}\cdot\text{lb}$$

$$= (5)(-80)(\underbrace{\hat{i} \times \hat{j}}_{\hat{k}}) + (5)(-40)(\underbrace{\hat{i} \times \hat{k}}_{-\hat{j}})$$

$$\vec{M}_O = (200\hat{j} - 400\hat{k}) \text{ lb}\cdot\text{ft}$$



### EXAMPLE # 3

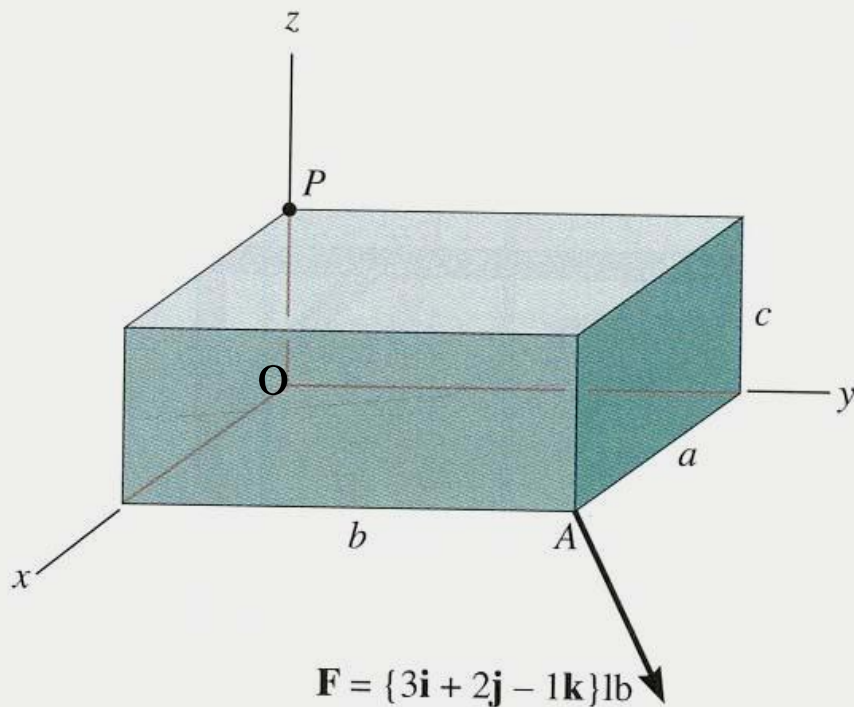
**Given:**  $a = 3$  in,  $b = 6$  in and  $c = 2$  in.

**Find:** Moment of  $F$  about point O.

**Plan:**

1) Find  $r_{OA}$ .

2) Determine  $M_O = r_{OA} \times F$ .



**Solution**  $r_{OA} = \{3\mathbf{i} + 6\mathbf{j} - 0\mathbf{k}\}$  in

$$\begin{aligned} M_O &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 3 & 6 & 0 \\ 3 & 2 & -1 \end{vmatrix} = [\{6(-1) - 0(2)\}\mathbf{i} - \{3(-1) - 0(3)\}\mathbf{j} + \\ &\quad \{3(2) - 6(3)\}\mathbf{k}] \text{ lb}\cdot\text{in} \\ &= \{-6\mathbf{i} + 3\mathbf{j} - 12\mathbf{k}\} \text{ lb}\cdot\text{in} \end{aligned}$$

